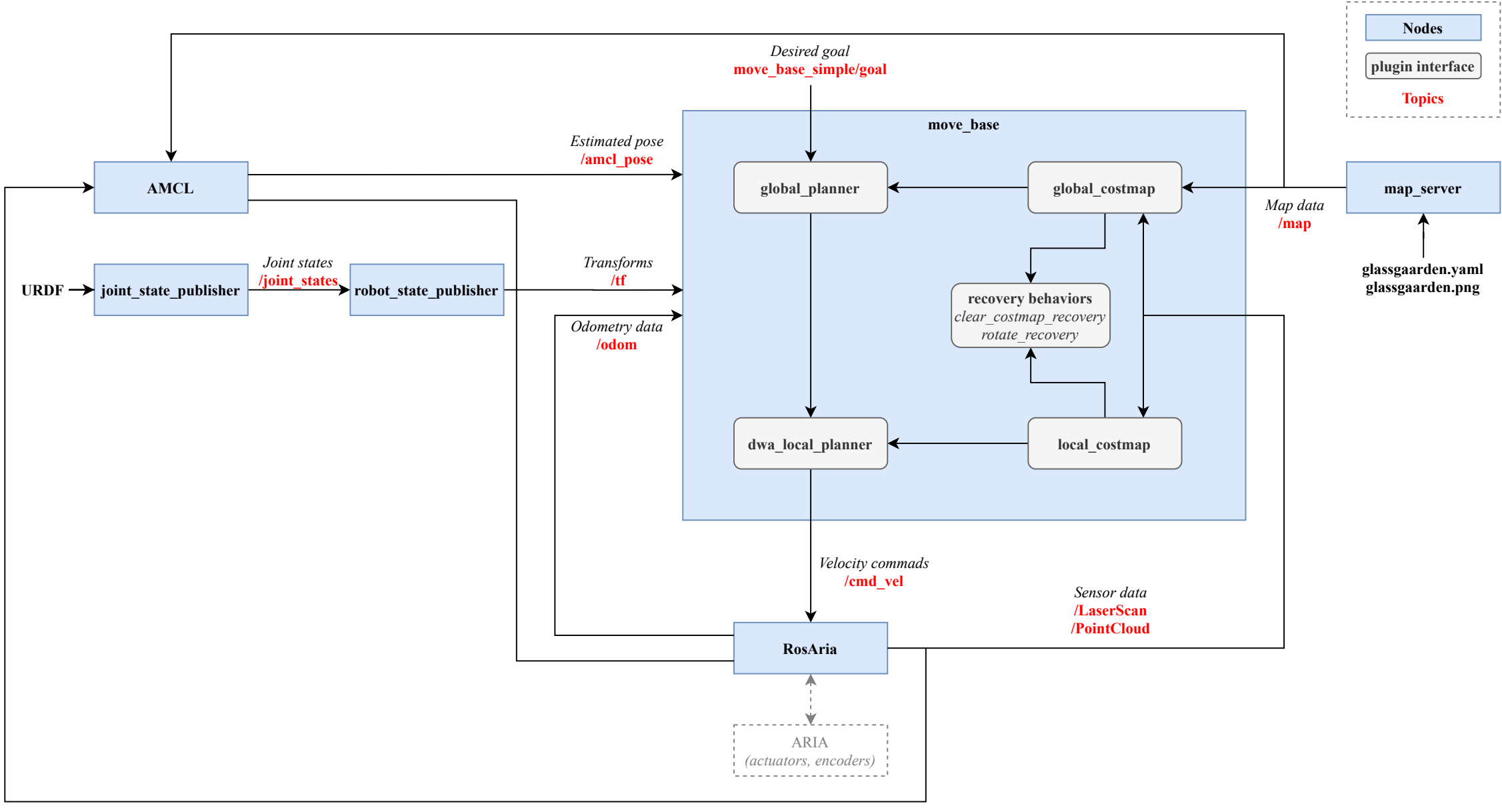
Nodes
plugin interface
Topics
Desired goal
move_base_simple/goal
move_base
Estimated pose
/amcl_pose
AMCL
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map_server
Map data
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URDF
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Joint states
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Transforms
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Odometry data
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dwa_local_planner
local_costmap
Velocity commads
/cmd_vel
Sensor data
/LaserScan
/PointCloud
RosAria
ARIA
(actuators, encoders)